## Name:

- 1. Let  $V = \{(x, y, z) \in \mathbb{R}^3 | x \neq 0 \text{ and } z \neq 0\}$ . And define the two operations
  - $\oplus$ :  $(x_1, y_1, z_1) \oplus (x_2, y_2, z_2) = (x_1 x_2, x_1 y_2 + y_1 z_2, z_1 z_2)$
  - $\odot: k \odot (x_1, y_1, z_1) = (kx_1, ky_1, kz_1)$
  - (a) Compute  $(0, 4, 4) \oplus (-1, 2, 3)$  and compute  $2 \odot (1, 1, 0)$ .
  - (b) Show  $\mathbf{0} \neq (0, 0, 0)$ .
  - (c) Show  $\mathbf{0} = (1, 0, 1)$ .

- 2. Let  $V = \{(x, y, z) \in \mathbb{R}^3 | x \neq 0 \text{ and } z \neq 0\}$ . And define the two operations
  - $\oplus: \quad (x_1, y_1, z_1) \oplus (x_2, y_2, z_2) = (x_1 x_2, x_1 y_2 + y_1 z_2, z_1 z_2)$
  - $\odot: k \odot (x_1, y_1, z_1) = (kx_1, ky_1, kz_1)$
  - (a) Prove that V is closed under  $\oplus$ .
  - (b) Prove that V is not closed under  $\odot$ .

3. Let  $W = \{(x, y, z) \in \mathbb{R}^3 : \text{ where } 2x + y = 0\}$ . Use the two step subspace test to show  $(W, +, \cdot)$  is a subspace of  $\mathbb{R}^3$ .

4. Let  $S = \{x, x + 2, x^2 - x - 1, x^2\}$  be a set in  $P_2$ . Show S linearly dependent by finding a nontrivial linear combination of the elements of S equal to zero.

5. The linear transformation  $T : \mathbb{R}^4 \to \mathbb{R}^3$  is given by the formula  $\begin{bmatrix} x \\ z \end{bmatrix}$ 

$$T\begin{pmatrix} x \\ y \\ z \\ w \end{bmatrix}) = \begin{bmatrix} x - 2w \\ w + z \\ x - 3z \end{bmatrix}.$$

- (a) Find the matrix, A, to represent the linear transformation T.
- (b) Compute the basis for the Range of T.
- (c) Find a basis for NULL(A).
- (d) Compute and compare Rank, Nullity and the dimension of the Domain.

- 6. Let  $B_1 = \{(0,1), (2,1)\}, B_2 = \{(2,-1), (2,0)\}$  and let B be the standard unit basis for  $\mathbb{R}^2$ .
  - (a) Find the change of basis matrices for  $P_{B_1 \to B_2}$  and  $P_{B_1 \to B_2}$ .
  - (b) The point  $(4,6)_{B_1} = 4(0,1) + 6(2,1) = (12,10)$  where (12,10) is given in the standard basis. Find the coordinates of  $(4,6)_{B_1}$  relative to the basis  $B_2$ .

- 7. Write the matrix for the following transformations described below.
  - (a)  $T: \mathbb{R}^2 \to \mathbb{R}^2$  where the plane is rotated by 30° counter-clockwise.
  - (b)  $T: \mathbb{R}^2 \to \mathbb{R}^2$  where the plane is reflected about the x-axis.
  - (c)  $T: \mathbb{R}^2 \to \mathbb{R}^2$  where the plane is rotated by 30° counter-clockwise and then reflected about the x-axis.
  - (d)  $T: \mathbb{R}^2 \to \mathbb{R}^2$  where the plane is reflected about the x-axis and then rotated by 30° counter-clockwise.